

Windowing Regularization Techniques for Unsteady Aerodynamic Shape Optimization

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Unsteady periodic flows

Many fluid flows in industry are unsteady and turbulent.

- Aerodynamic design of rotor-craft
- Wind turbine design
- Flows around bluff bodies, e.g. airfoil at high angle of attack

Unsteady periodic flows

Many fluid flows in industry are unsteady and turbulent.

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- Flows around bluff bodies, e.g. airfoil at high angle of attack

/ URANS flow simulations for separated flows result in periodic flow fields.

/ Flow field is smooth with clear periodicity.

(a) Snapshot at start of period

(b) at $1=3$ of period

(c) and at $2=3$ of period

Kármán vortex street behind airfoil) Undesirable!

Optimization objective in periodic flows

- Flow fields are often periodic after a transient time $t_{tr} = n_{tr} \Delta t$.
 - Flow outputs such as Drag C_D or Lift C_L are periodic.
 - Their sensitivities $\frac{d}{d} C_D$ and $\frac{d}{d} C_L$ w.r.t. design vector are periodic.
- ! Optimization objective: Outputs averaged over a period.

$$J(\mathbf{x}; C_D) = \frac{1}{T(\mathbf{x})} \int_{t_{tr}}^{T(\mathbf{x}) + t_{tr}} C_D(t; \mathbf{x}) dt \quad (1)$$

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- Period length $T(\mathbf{x})$ unknown and dependent on \mathbf{x} !
- How to compute the sensitivity?

$$\frac{d}{d} J(\mathbf{x}; C_D) = \frac{d}{d} \frac{1}{T(\mathbf{x})} \int_{t_{tr}}^{T(\mathbf{x}) + t_{tr}} C_D(t; \mathbf{x}) dt \quad (2)$$

Finite time averaging

! Average over finite time M and hope for convergence as $M \rightarrow \infty$,

$$J_M(\mathbf{x}; M; C_D) = \frac{1}{M} \int_{t_{tr}}^M C_D(t; \mathbf{x}) dt \quad (3)$$

■ Similar for time averaged sensitivity

$$\frac{d}{d\mathbf{x}} J_M(\mathbf{x}; M; C_D) = \frac{1}{M} \int_{t_{tr}}^M \frac{d}{d\mathbf{x}} C_D(t; \mathbf{x}) dt \quad (4)$$

Convergence properties

- Amplitude change in $\frac{d}{d} C_D$
- Increase M for convergence of $J_M(; M; C_D)$ and $\frac{d}{d} J_M()$?

¹Wilkins, A., Tidor, B., White, J. and Barton, P. , "Sensitivity Analysis for Oscillating Dynamical Systems", *SIAM Journal on Scientific Computing*, Vol. 31, No.4, 2009, pp. 2706-2732

Convergence properties

- Amplitude change in $\frac{d}{d} C_D$
- Increase M for convergence of $J_M(\cdot; M; C_D)$ and $\frac{d}{d} J_M(\cdot)$?
- Fast growth in amplitude from sensitivity of phase and period length¹.
- Last values of $\frac{d}{d} C_D$ distort sensitivity results

$$J_M(\cdot) \approx M!^{-1} J(\cdot), \text{ but } \frac{d}{d} J_M(\cdot) \approx M!^{-1} \frac{d}{d} J(\cdot)$$

¹Wilkins, A., Tidor, B., White, J. and Barton, P., "Sensitivity Analysis for Oscillating Dynamical Systems", *SIAM Journal on Scientific Computing*, Vol. 31, No.4, 2009, pp. 2706-2732

Long time windowing by Krakos et al.²

! **Weighted** average over finite time M and hope for convergence as $M \rightarrow \infty$,

$$J_w(\cdot; M; C_D) = \frac{1}{M} \int_{t_{tr}}^{M+t_{tr}} w \left(\frac{t - t_{tr}}{M} \right) C_D(t; \cdot) dt: \quad (5)$$

■ Similar for time averaged sensitivity,

$$\frac{d}{d} J_w(\cdot; M; C_D) = \frac{1}{M} \int_{t_{tr}}^{M+t_{tr}} w \left(\frac{t - t_{tr}}{M} \right) \frac{d}{d} C_D(t; \cdot) dt: \quad (6)$$

²Krakos, J., Wang, Q., Hall, S. and Darmofal L. "Sensitivity analysis of limit cycle oscillations", *Journal of Computational Physics*, Vol. 231 (2012), 3228-3245

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■ $w(\cdot) \in C^k$, $w(\cdot) = 1$ at $t=M$ is the **windowing function** with

$$\int_0^1 w(\tau) d\tau = 1 \quad \text{and} \quad w(\tau) = 0; \quad \tau \in \mathbb{R} \setminus (0;1) \quad (7)$$

! $w = 1_{(0;1)} \in C^{k=0}$ denotes a piecewise continuous window. (Finite time averaging is just a special case!)

²Krakos, J., Wang, Q., Hall, S. and Darmofal L. "Sensitivity analysis of limit cycle oscillations", *Journal of Computational Physics*, Vol. 231 (2012), 3228-3245

Convergence of long time windowing

- Convergence order depends on the smoothness of the windowing function $w \in C^k$.

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Convergence of long time windowing

- Convergence order depends on the smoothness of the windowing function $w \in C^k$.

Theorem (Kraos et al. ²)

Let h be the period normalized flow output and $w \in C^k$. The windowed average error bound is given by

$$|J_w(\cdot; M) - J(\cdot)| \leq kh_1 O(M^{-p}); \quad (8)$$

$$\left| \frac{d}{d} J_w(\cdot; M) - \frac{d}{d} J(\cdot) \right| \leq k_0 kh_1 O(M^{-p}) + \frac{1}{T} \frac{dT}{d} \bigg|_1 kh_1 O(M^{-(p-1)}) \quad (9)$$

where

$$p = \begin{cases} 1; & k = 1; \\ k+1; & k = 0; k \text{ even}; \\ k+2; & k > 0; k \text{ odd}; \end{cases} \quad (10)$$

! No convergence for traditional finite time average given!

²Kraos, J., Wang, Q., Hall, S. and Darmofal L. "Sensitivity analysis of limit cycle oscillations", *Journal of Computational Physics*, Vol. 231 (2012), 3228-3245

Mathematical formulation of the optimization problem

$$\min \quad J_w(u(\cdot); \cdot; M; C_D) \quad (11a)$$

$$s:t: \quad u^n = G(u^n; \cdot; u^{n-1}; u^{n-2}); \quad n = 1; \dots; N \quad (11b)$$

$$J_w(u(\cdot); \cdot; M; C_L) \leq c \quad c \in \mathbb{R} \quad (11c)$$

- Discretize windowed objective with midpoint rule,

$$J_w(C_D) \approx \frac{1}{N} \sum_{n=n_{tr}}^{N} w \frac{n}{N} \frac{n_{tr}}{n_{tr}} C_D(u^n; \cdot) \quad (12)$$

- Flow constraint in fixed point formulation with 2nd order BDF method,

$$u^n = G(u^n; \cdot; u^{n-1}; u^{n-2}); \quad (13)$$

- Inequality constraints as windowed lift,

$$J_w(u(\cdot); \cdot; M; C_L) \leq c \quad (14)$$

Lagrange approach

- Compute descent direction $\frac{d}{d} J_w$ for optimization.
 - Avoid expensive gradients like $\frac{d}{d} u^n$, that appear using the chain rule.
- ! Lagrange Function reads

$$L([u^1; \dots; u^n]^T; [\bar{u}^1; \dots; \bar{u}^n]^T) = J_w(u; M; C_D) + \sum_{n=1}^N (\bar{u}^n)^T G u^n; u^{n-1}; u^{n-2} \quad u^n \quad (15)$$

Lagrange approach

- Compute descent direction $-\frac{d}{d} J_w$ for optimization.
 - Avoid expensive gradients like $\frac{d}{d} u^n$, that appear using the chain rule.
- ! Lagrange Function reads

$$L([u^1; \dots; u^n]^T; [\bar{u}^1; \dots; \bar{u}^n]^T) = J_w(u; M; C_D) + \sum_{n=1}^N (\bar{u}^n)^T G u^n; u^{n-1}; u^{n-2} \quad u^n \quad (15)$$

- Solve the KKT System

$$\frac{\partial L}{\partial u^n} = 0; \quad n = 1; \dots; N \quad \text{state equations} \quad (16a)$$

$$\frac{\partial L}{\partial \bar{u}^n} = 0; \quad n = 1; \dots; N \quad \text{adjoint equations} \quad (16b)$$

$$\frac{\partial L}{\partial \lambda} = 0; \quad \text{design equation} \quad (16c)$$

Adjoint Sensitivity Computation

- Adjoint equations (adjoint iterator), given by $@_{U^n} L = 0$,

$$\bar{u}_{p+1}^n = H \bar{u}_p^n ; \bar{u}^{n+1} ; \bar{u}^{n+2} ; \quad n = 1 ; \dots ; N : \quad (17)$$

Adjoint Sensitivity Computation

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$$\bar{u}_{p+1}^n = H \bar{u}_p^n; \bar{u}^{n+1}; \bar{u}^{n+2} ; \quad n = 1; \dots; N: \quad (17)$$

- In detail, we have

$$\begin{aligned}
 @_{U^n} L = & \bar{u}^n + \underbrace{(\underbrace{z}_{\text{from 2nd order BDF method in direct iterator}} @_{U^n} G^n)^T}_{\text{independent of } \bar{u}^n} \bar{u}^n + @_{U^n} G^{n+1} \underbrace{T}_{\text{independent of } \bar{u}^n} \bar{u}^{n+1} + @_{U^n} G^{n+2} \underbrace{T}_{\text{independent of } \bar{u}^n} \bar{u}^{n+2} \\
 & + \underbrace{1}_{\text{independent of } \bar{u}^n} \underbrace{f_n}_{\text{independent of } \bar{u}^n} \underbrace{n_{trg}}_{\text{independent of } \bar{u}^n} \underbrace{\frac{1}{N}}_{\text{independent of } \bar{u}^n} \underbrace{w}_{\text{independent of } \bar{u}^n} \underbrace{\frac{n}{N}}_{\text{independent of } \bar{u}^n} \underbrace{\frac{n_{tr}}{n_{tr}}}_{\text{independent of } \bar{u}^n} (@_{U^n} C_D(u^n;))^T : \quad (18)
 \end{aligned}$$

Adjoint Sensitivity Computation

- Adjoint equations (adjoint iterator), given by $@_{U^n} L = 0$,

$$\bar{u}_{p+1}^n = H \bar{u}_p^n; \bar{u}^{n+1}; \bar{u}^{n+2} ; \quad n = 1; \dots; N: \quad (17)$$

- In detail, we have

$$\begin{aligned}
 @_{U^n} L = & \underbrace{\bar{u}^n + (@_{U^n} G^n)^T \bar{u}^n + @_{U^n} G^{n+1}^T \bar{u}^{n+1} + @_{U^n} G^{n+2}^T \bar{u}^{n+2}}_{\substack{\text{from 2}^{nd} \text{ order BDF method in direct iterator} \\ \{ \\ \}}}} \\
 & + \underbrace{1}_{f_n} \underbrace{\frac{n}{N}}_{n_{tr}g} \underbrace{\frac{1}{N}}_w \underbrace{\frac{n}{N} \frac{n_{tr}}{n_{tr}}}_{\{Z}} (@_{U^n} C_D(U^n;))^T : \quad (18) \\
 & \underbrace{\hspace{10em}}_{\text{independent of } \bar{u}^n}
 \end{aligned}$$

- Contractivity of H^n ? / Given by contractivity of G^n ,

$$k_{@_{U^n} H^n} k = (@_{U^n} G^n)^T = k(@_{U^n} G^n) k: \quad (19)$$

/ Adjoint iterator H^n inherits convergence of direct iterator G^n regardless of the chosen window.

Adjoint Sensitivity Computation

- Design equation is given by @ L ,

$$\textcircled{L} = \sum_{n=0}^N \frac{1}{N} \frac{n}{N} \frac{n_{tr}}{n_{tr}} w \textcircled{C}_D(u^n; \cdot) + (\bar{u}^n)^T \textcircled{G}^n \quad (20)$$

! Windowing function $w \frac{n}{N} \frac{n_{tr}}{n_{tr}}$ only appears as a *seeding* factor. ! super cheap!

! Only one floating point operation difference to traditional adjoint.

! Easy to implement.

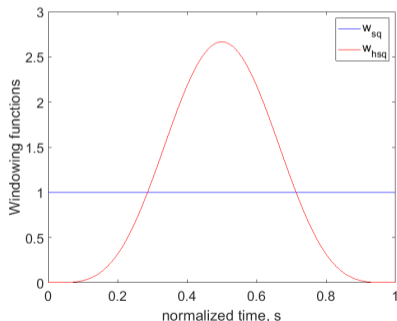
```
seedi ng = wi ndowEval uator. GetWndWei ght(n, N, n_tr) / (N-n_tr);
```

Test Case - NACA0012 Airfoil with high angle of attack³

- URANS Flow solver with JST flux.
- Spalart-Allmaras turbulence model with upwind flux.
- Reynolds number is 10^6 , Mach number is 0.3.

Used windowing functions

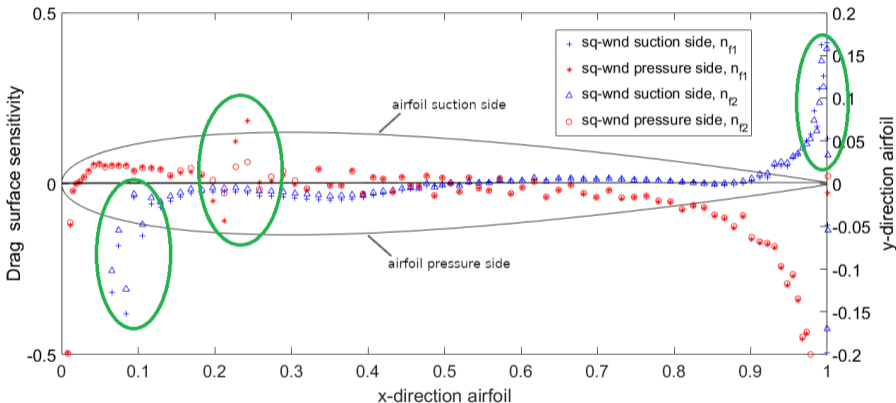
- Square: $w_{sq} \in C^1$
 -) $J_{w_{sq}}$ converges in $O(M^{-1})$
 -) @ $J_{w_{sq}}$ converges in $O(M^0)$
- Hann-Square: $w_{hsq} \in C^3$
 -) $J_{w_{hsq}}$ converges in $O(M^{-5})$
 -) @ $J_{w_{hsq}}$ converges in $O(M^{-4})$Period boundaries are weighted less than the middle of the period.



³Resources online at https://su2code.gi.thub.uni-kl.de/tutorials/Unsteady_Shape_Opt_NACA0012/

Surface Sensitivities - Square Windowing

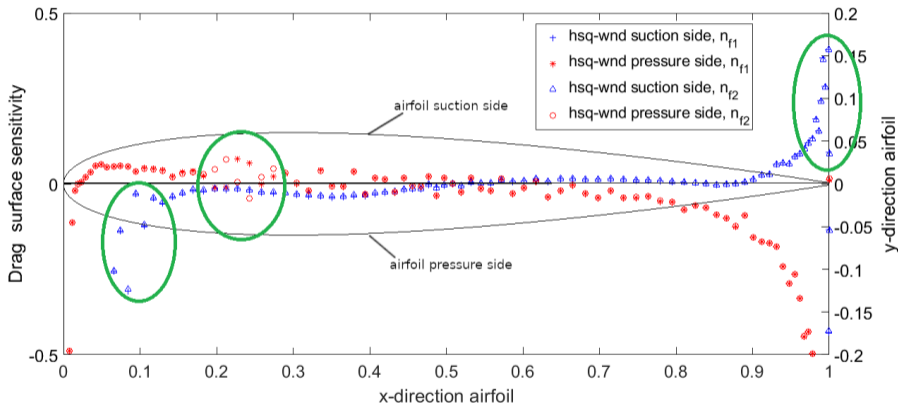
- Sensitivities of airfoil surface at final iterations n_{f1} and n_{f2} , where $n_{f2} = n_{f1} + 3T$.



- **Great difference** of surface sensitivities for different final iterations!
- Square windowing is **very sensitive** w.r.t. choice of final iteration n_f .

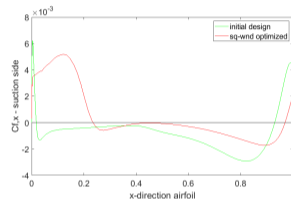
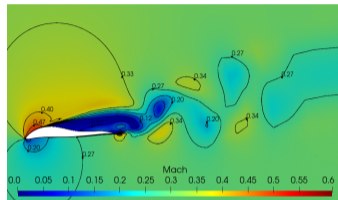
Surface Sensitivities - Hann-Square Windowing

- Sensitivities of airfoil surface at final iterations n_{f1} and n_{f2} , where $n_{f2} = n_{f1} + 3T$.



- **Small difference** of surface sensitivities for different final iterations!
- Hann-Square windowing is **robust** w.r.t. choice of final iteration n_f . ! Good for shape optimization!

Optimization Result - Square Windowing



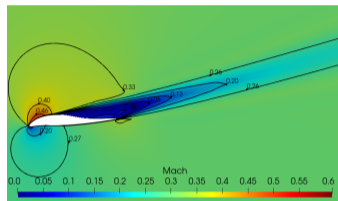
(a) Initial design

(b) After 15 design iterations

(c) Skin friction coefficient, x dir.

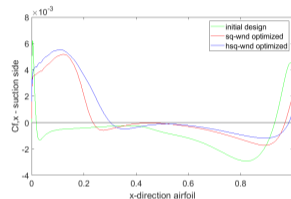
- Small reduction of the vortex street, still periodic behavior.
- $C_f; x$ has sign change at 23% airfoil length.
- The flow detaches itself further back on the wing than in the initial design.

Optimization Result - Hann-Square Windowing



(a) Initial design

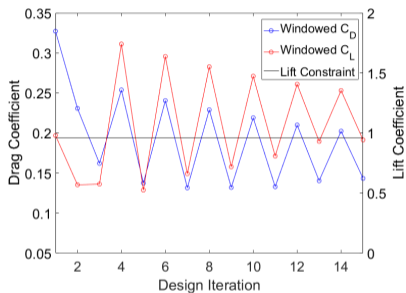
(b) After 15 design iterations



(c) Skin friction coefficient, x dir.

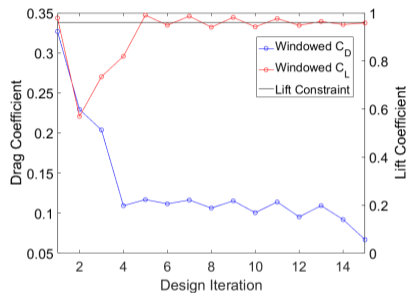
- Optimized flow is in steady state, no vortices left.
- $Cf; x$ has sign change at 30% airfoil length.
- The flow detaches itself 50% further back on the wing than in the Square windowed design.

Comparison of Design Processes



Square windowing

- ca. 59% drag reduction.
- Many designs infeasible (line search fails).
- Low Drag) low Lift.



Hann-Square windowing

- ca. 81% drag reduction.
- Almost all designs feasible.
- Low Drag, but high Lift.

) Similar results for other high order windows.

Windowing in SU2 - Usage and Implementation

- Two possibilities in SU2.
 - ! Adjoint sensitivity computation via Lagrange approach and automatic differentiation.
 - ! Windowed time averages of flow outputs or
Windowed time averages of sensitivities via direct (tangent) sensitivity computation via AD (forward mode).
- Managed by Class `CWindowingTools` ! Easy to add new windowing functions!

Windowing in SU2 - Adjoint mode and shape optimization³

- Define your windowing function `WINDOW_FUNCTION = HANN`
- Specify the final time iteration for the direct run
`TIME_ITER = 1200`
- Specify the iteration to start the time average (after transient phase is over) `WINDOW_START_ITER = 500`
- Specify the iteration to start adjoint run
`UNST_ADJOINT_ITER = 1200`
- Specify the window length `M_ITER_AVERAGE_OBJ = 700`
- Choose the optimization objective `OPT_OBJECTIVE = DRAG * 1.0`

³Resources online at https://su2code.github.io/tutorials/Unsteady_Shape_Opt_NACA0012/

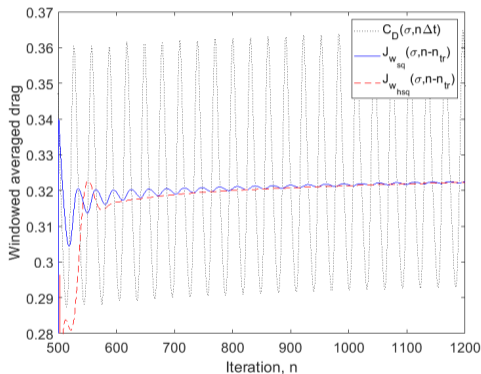
Windowing in SU2 - Direct mode⁴

- ! Postprocessing step of the direct solver at each time iteration.
 Compute $u^n = G(u^n; :::)$, then the *running* windowed average $J_w(u; n - n_{tr}; C_D)$.
- Define your windowing function `WINDOW_FUNCTION = HANN_SQUARE`
- Define the iteration to start the time average (after transient phase is over) `WINDOW_START_ITER = 500`
- Choose output groups/fields to average by using the prefix `TAVG_` (time average) and `D_TAVG_` (time averaged sensitivity)
 - `SCREEN_OUTPUT = (TAVG_DRAG, D_TAVG_DRAG, ...)`
 - `HISTORY_OUTPUT = (TAVG_AEROCOEFF, D_TAVG_AEROCOEFF, ...)`
- Value is the windowed average from `WINDOW_START_ITER` up to the current iteration.
 - ! Can be used for time convergence monitoring!

⁴Resources online at https://su2code.github.io/tutorials/Unsteady_NACA0012/

Windowing in SU2 - Direct mode convergence monitoring⁴

- Idea: Output values should be a Cauchy sequence.
- Activate the window convergence criterion.
`WINDOW_CAUCHY_CRIT = YES`
- Specify convergence field(s).
`CONV_WINDOW_FIELD = (TAVG_DRAG, D_TAVG_LIFT)`
- Specify the number of elements to apply the criterion.
`CONV_WINDOW_CAUCHY_ELEMS = 100`
- Set Epsilon to control the series convergence.
`CONV_WINDOW_CAUCHY_EPS = 1E-2`



Convergence of windowed Averages

⁴Resources online at https://su2code.github.io/tutorials/Unsteady_NACA0012/

Windowing in SU2 - Efficient shape optimization workflows

Simulation

- Get **end of transient phase** n_{tr} (plus some buffer iterations).
- Save restart files, to avoid computing the transient phase in each design iteration.

Direct Differentiation

- Use windowed time convergence monitoring for sensitivity of objective function.
- Get **minimal number** N_{min} **of time iterations** needed for a converged windowed sensitivity.

Shape optimization

- Use restart files to skip transient phase in each design iteration.
- Use **minimal time frame** (plus some buffer iterations) for discrete adjoint computation, i.e. $M = (N_{min} + buffer) - (n_{tr} + buffer)$ and **save computational time**.

Summary and Conclusion

- Traditional time averages fail to compute sensitivities correctly in periodic flows.
- Long time windowing yields **faster convergence** of period averages and **correct sensitivities**.
- Windowing is **easy to embed** in adjoint sensitivity solvers.
- Windowing gives **more robust** surface sensitivities with respect to changing final times.
- Windowed shape optimization processes converge faster and are able to fulfill design constraints.
 - ! The traditional approach fails to do this.
- Future work: Extension to DES flows. DES flows resolve multiple vortex scales.
 - ! Decompose flow field into base frequencies and apply windowing.

Thank you for your attention!